attiny.motor(„A/B/AB“, 0-100/0-1, “analog/digital“)

delay (čas)

#include <Attiny85\_IO.h>

void setup() { }

void loop() {}

attiny.LightSensor(1/2,“analog/digital“)

if (){}

else if () {}

else {}

https://raw.githubusercontent.com/damellis/attiny/ide-1.6.x-boards-manager/package\_damellis\_attiny\_index.json